G05EAF - NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

G05EAF sets up a reference vector for a multivariate Normal distribution with mean vector a and covariance matrix C, so that G05EZF may be used to generate pseudo-random vectors.

2 Specification

SUBROUTINE GO5EAF(A, N, C, IC, EPS, R, NR, IFAIL)
INTEGER
N, IC, NR, IFAIL

real
A(N), C(IC,N), EPS, R(NR)

3 Description

When the covariance matrix is non-singular (i.e., strictly positive-definite), the distribution has probability density function

$$f(x) = \sqrt{\frac{|C^{-1}|}{(2\pi)^n}} \exp\left\{-(x-a)^T C^{-1} (x-a)\right\}$$

where n is the number of dimensions, C is the covariance matrix, a is the vector of means and x is the vector of positions.

Covariance matrices are symmetric and positive semi-definite. Given such a matrix C, there exists a lower triangular matrix L such that $LL^T = C$. L is not unique, if C is singular.

G05EAF decomposes C to find such an L. It then stores n, a and L in the reference vector r for later use by G05EZF. G05EZF generates a vector x of independent standard Normal pseudo-random numbers. It then returns the vector a + Lx, which has the required multivariate Normal distribution.

It should be noted that this routine will work with a singular covariance matrix C, provided C is positive semi-definite, despite the fact that the above formula for the probability density function is not valid in that case. Wilkinson [2] should be consulted if further information is required.

4 References

- [1] Knuth D E (1981) The Art of Computer Programming (Volume 2) Addison-Wesley (2nd Edition)
- [2] Wilkinson J H (1965) The Algebraic Eigenvalue Problem Oxford University Press, London

5 Parameters

1: A(N) — real array Input

On entry: the vector of means, a, of the distribution.

2: N — INTEGER Input

On entry: the number of dimensions, n, of the distribution.

Constraint: N > 0.

3: C(IC,N) — real array

On entry: the covariance matrix of the distribution. Only the upper triangle need be set.

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4: IC — INTEGER Input

On entry: the first dimension of the array C as declared in the (sub)program from which G05EAF is called.

Constraint: $IC \geq N$.

5: EPS - real Input

On entry: the maximum error in any element of C, relative to the largest element of C.

Constraint: $0.0 \le EPS \le 0.1/N$.

If EPS is less than *machine precision*, *machine precision* is used.

6: R(NR) - real array

Output

On exit: the reference vector for subsequent use by G05EZF.

7: NR - INTEGER Input

On entry: the dimension of the array R as declared in the (sub)program from which G05EAF is called.

Constraint: $NR \ge ((N + 1) \times (N + 2))/2$.

8: IFAIL — INTEGER Input/Output

On entry: IFAIL must be set to 0, -1 or 1. For users not familiar with this parameter (described in Chapter P01) the recommended value is 0.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors detected by the routine:

IFAIL = 1

On entry, N < 1.

IFAIL = 2

On entry, $NR < ((N + 1) \times (N + 2))/2$.

IFAIL = 3

On entry, IC < N.

IFAIL = 4

On entry, EPS < 0.0, or EPS > 0.1/N.

IFAIL = 5

The covariance matrix C is not positive semi-definite to accuracy EPS.

7 Accuracy

The maximum absolute error in LL^T , and hence in the covariance matrix of the resulting vectors, is less than $(n \times \max(\text{EPS}, \epsilon) + (n+3)\epsilon/2)$ times the maximum element of C, where ϵ is the **machine precision**. Under normal circumstances, the above will be small compared to sampling error.

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8 Further Comments

The time taken by the routine is of order n^3 .

It is recommended that the diagonal elements of C should not differ too widely in order of magnitude. This may be achieved by scaling the variables if necessary. The actual matrix decomposed is $C+E=LL^T$, where E is a diagonal matrix with small positive diagonal elements. This ensures that, even when C is singular, or nearly singular, the Cholesky Factor L corresponds to a positive-definite covariance matrix that agrees with C within a tolerance determined by EPS.

9 Example

The example program prints five pseudo-random observations from a bivariate Normal distribution with means vector

 $\begin{bmatrix} 1.0 \\ 2.0 \end{bmatrix}$

and covariance matrix

$$\begin{bmatrix} 2.0 & 1.0 \\ 1.0 & 3.0 \end{bmatrix}$$

generated by G05EAF and G05EZF after initialisation by G05CBF.

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
GO5EAF Example Program Text
  Mark 14 Revised. NAG Copyright 1989.
   .. Parameters ..
  INTEGER
                    N, IC, NR
  PARAMETER
                    (N=2, IC=N, NR=(N+1)*(N+2)/2)
  INTEGER
                    NOUT
  PARAMETER
                    (NOUT=6)
   .. Local Scalars ..
  INTEGER
                    I, IFAIL, J
   .. Local Arrays ..
                    A(N), C(IC,N), R(NR), Z(N)
  real
   .. External Subroutines ..
  EXTERNAL
                    GO5CBF, GO5EAF, GO5EZF
   .. Executable Statements ...
  WRITE (NOUT,*) 'GO5EAF Example Program Results'
  WRITE (NOUT,*)
  A(1) = 1.0e0
  A(2) = 2.0e0
  C(1,1) = 2.0e0
  C(2,2) = 3.0e0
  C(1,2) = 1.0e0
  C(2,1) = 1.0e0
  CALL GO5CBF(0)
  IFAIL = 0
  CALL GOSEAF(A,N,C,IC,0.01e0,R,NR,IFAIL)
  DO 20 I = 1, 5
      IFAIL = 0
     CALL GO5EZF(Z,N,R,NR,IFAIL)
     WRITE (NOUT, 99999) (Z(J), J=1, N)
20 CONTINUE
```

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```
* 99999 FORMAT (1X,2F10.4)
END
```

9.2 Program Data

None.

9.3 Program Results

GO5EAF Example Program Results

1.7697	4.4481
3.2678	3.0583
3.1769	2.3651
-0.1055	1.8395
1.2933	-0.1850

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